



**CERTIFICATE OF MAILING**

I hereby certify that this paper and every paper referred to therein as being enclosed is being placed in First Class Mail addressed to the Commissioner for Patents, P.O. Box 1450, Alexandria, VA. 22313-1450 as of today.

  
Richard T. Lyon

Date: 10-27-03

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2858

**PATENT**

Microsoft Docket No. 146837.2  
L&H No. MCS-120-99

**IN THE UNITED STATES PATENT AND TRADEMARK OFFICE**

In re Application of  
Meyers, et al.

Group Art Unit: 2858

Entitled: GEOMETRIC MODEL  
DATABASE FOR USE IN UBIQUITOUS  
COMPUTING

Examiner: Unknown

2123  
Thangavelu

Serial No.: 09/657,871

Filing Date: September 8, 2000

**SUPPLEMENTAL INFORMATION DISCLOSURE STATEMENT UNDER 37 CFR**

**1.97(b)**

Commissioner of Patents  
P.O. Box 1450  
Alexandria, VA 22313-1450

Sir:

Attached hereto is Form PTO-1449 listing documents believed relevant to the subject application. It is respectfully requested that these documents be made of record and an initialed copy of each form be returned to the undersigned.

This disclosure statement should not be construed as a representation that a search has been made or that no other material information as defined in 37 CFR 1.56(a) exists.


Furthermore, no admission is being made that these documents are prior art, and applicant reserves the right to challenge any such conclusion.

It is believed that this disclosure complies with the requirements of 37 CFR 1.56, 1.97, and 1.98, and the manual of Patent Examining Procedures, section 609 and 707.05. If for some reason the Examiner considers otherwise, it is respectfully requested that the undersigned be called so that any deficiencies can be remedied.

A copy of each document is enclosed unless indicated otherwise. Some of the documents may have markings on them. No significance is meant to be attached to the markings. These documents are not necessarily analogous art.

LYON & HARR, LLP  
300 Esplanade Drive  
Suite 800  
Oxnard, CA 93036  
(805) 278-8855

Respectfully submitted



Richard T. Lyon  
Reg. No. 37,385  
Attorney for Applicant(s)

**GROUP:**  
**2858**

*Examiner Initial	Ref.	Document Number	Date	Name	Class	Subclass	Filing Date (If Appropriate)
	A1	5,850,352	12/15/98	Moezzi et al.			11/06/95

[illegible]

A2	Chavand, F., Ollier, J. M., Lelandais, S., Updating the environment's geometric database in telerobotics: Determination for position-orientation of known objects, <i>IEEE International Conference on Systems, Man and Cybernetics</i> , San Antonio, Texas, 1994, pp. 1351-1356.
A3	Lin, I-S., F. Wallner, R. Dillman, Interactive control and environment modelling for a mobile robot based on multisensor perceptions, <i>Robotics and Autonomous Systems</i> , 1996, vol. 18, pp. 301-310.

DATE CONSIDERED:

Sheet 1 of 1